

Event-driven automation and orchestration

@GRNET

with Stackstorm

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what we have

what we have

- ~50 carrier routers

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- ~150 access switches

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- ~50 carrier routers
- ~150 access switches
- ~60 datacenter switches

what we have

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- Ansible for config management

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- Git for VCS

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- Ansible for config management
- Git for VCS
- Tools managing network infrastructure and services

and common workflows...

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- deployment of new services

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- provisioning of new devices/replacement of faulty ones

and common workflows...

- deployment of new services
- provisioning of new devices/replacement of faulty ones
- software upgrades

...that

...that

- are well defined

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- consume time and human effort

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- although, can be scripted (eg. in runbooks)

some of our use cases

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- Datacenter switches mass upgrade

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- Zero Touch Provisioning

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- Auto-deployment of our Ansible repo changes

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- Zero Touch Provisioning
- Auto-deployment of our Ansible repo changes
- Network Ops tasks part of BMS autoprovision

So...

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...let's automate

we need a tool that

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- **trigger actions** based on them
- can abstract **actions** into complex **workflows**
- interact with the network and our tools

Stackstorm

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- Lots of intergration with other tools (ST2 calls them **packs**)
- Support for "standard" workflow language (Openstack's **Mistral**)
- Native intergration with network infrastructure (with **NAPALM** pack)

Stackstorm

“ IF-This-Then-That automation

Sensors

Inbound/Outbound intergration.
Receive/poll for events.

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Triggers

Result of an activated sensor.

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Triggers

Result of an activated sensor.

Actions

Outbound intergrations. A REST API call, an ansible playbook or a custom script.

Rules

Map triggers to actions. Filter against criteria and pass trigger data to the actions run

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Workflows

A connected set of actions.

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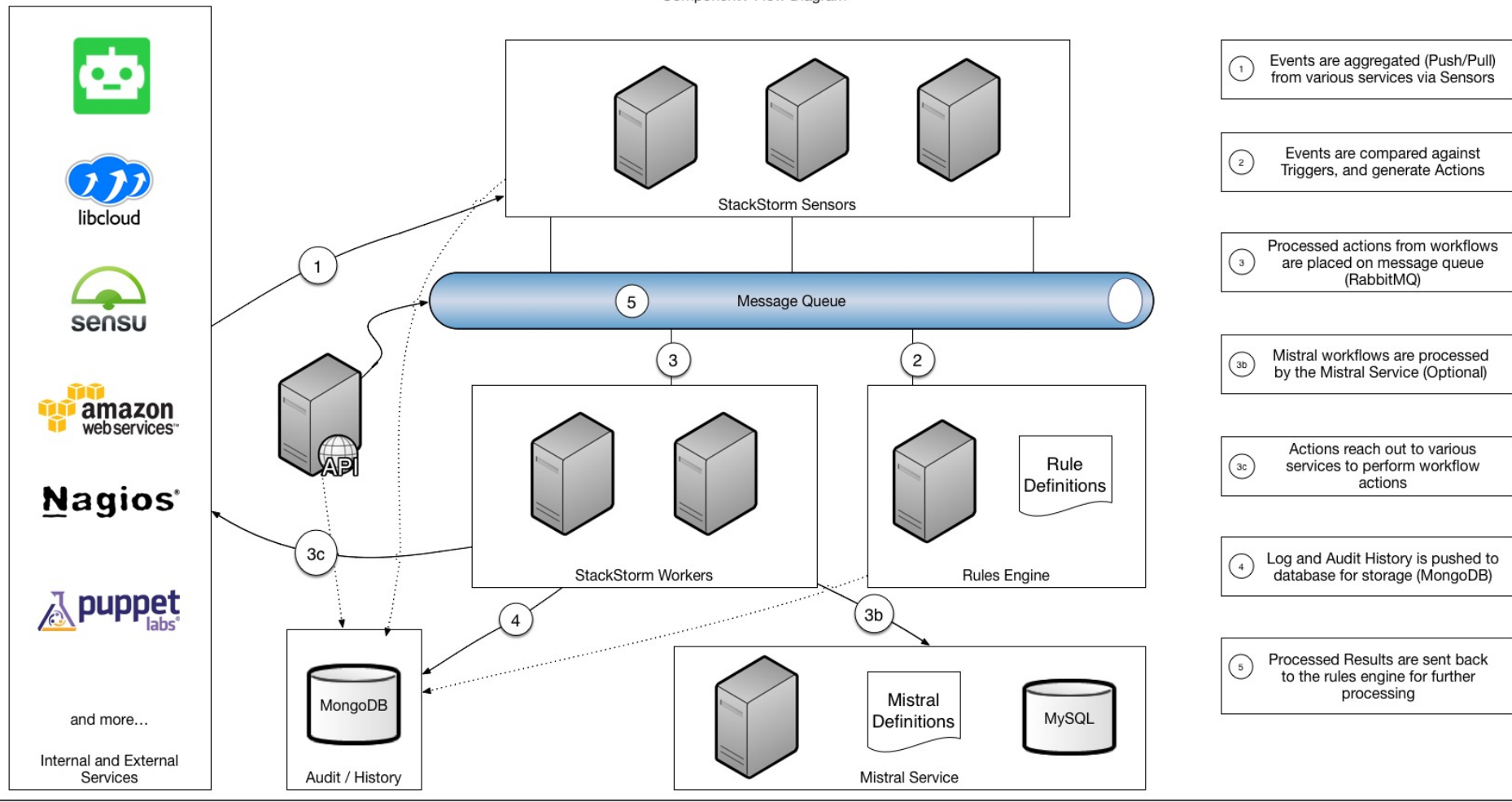
Packs

Units of content deployment.
Eq. to a module or a plugin.

Architecture



Component / Flow Diagram



The anatomy of a pack

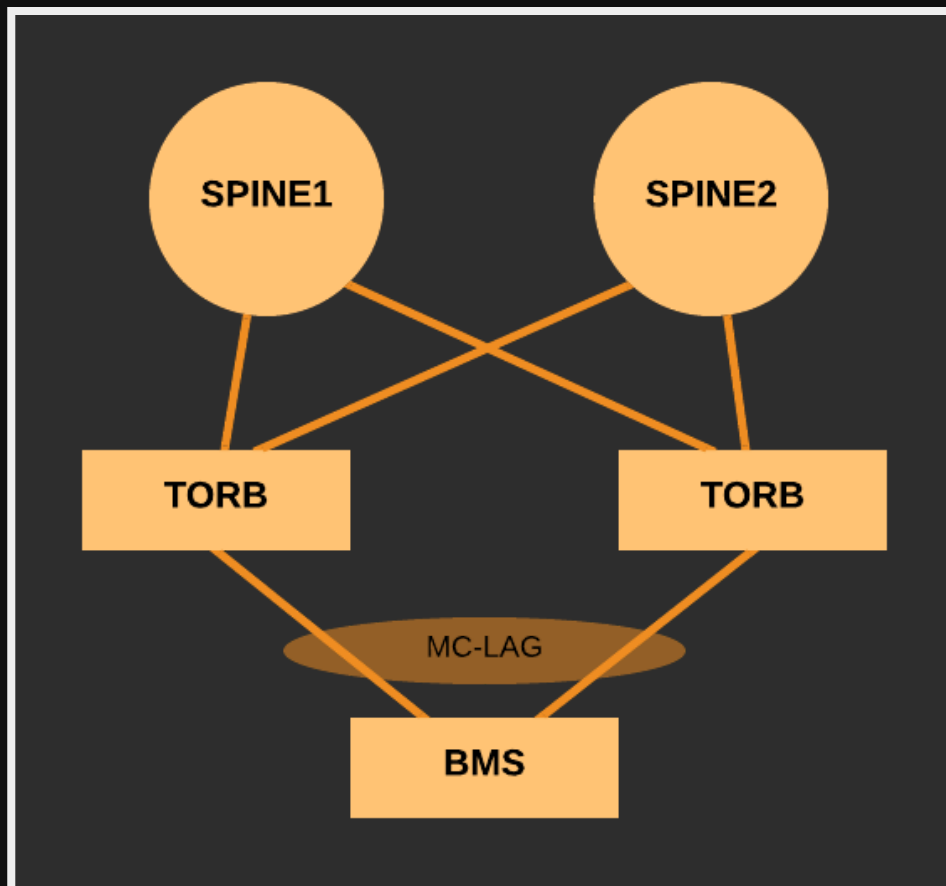
```
├── actions
│   ├── drain-leaf.meta.yaml
│   ├── evaluate_bgp_peers_status.py
│   ├── evaluate_bgp_peers_status.yaml
│   ├── junos-upgrade.meta.yaml
│   ├── undrain-leaf.meta.yaml
│   └── upgrade-leaf.meta.yaml
├── workflows
│   ├── drain-leaf.yaml
│   ├── junos-upgrade.yaml
│   ├── mistral-leaf-ztp.yaml
│   ├── undrain-leaf.yaml
│   └── upgrade-leaf.yaml
```

The anatomy of a pack

```
|
|— icon.png
|— pack.yaml
|— requirements.txt
|— rules
|   |— drain_leaf.yaml
|   |— fabric_leaf_ztp.yaml
|   |— junos_upgrade.yaml
|   |— undrain_leaf.yaml
|   |— upgrade_fabric.yaml
|   |— upgrade_leaf.yaml
```

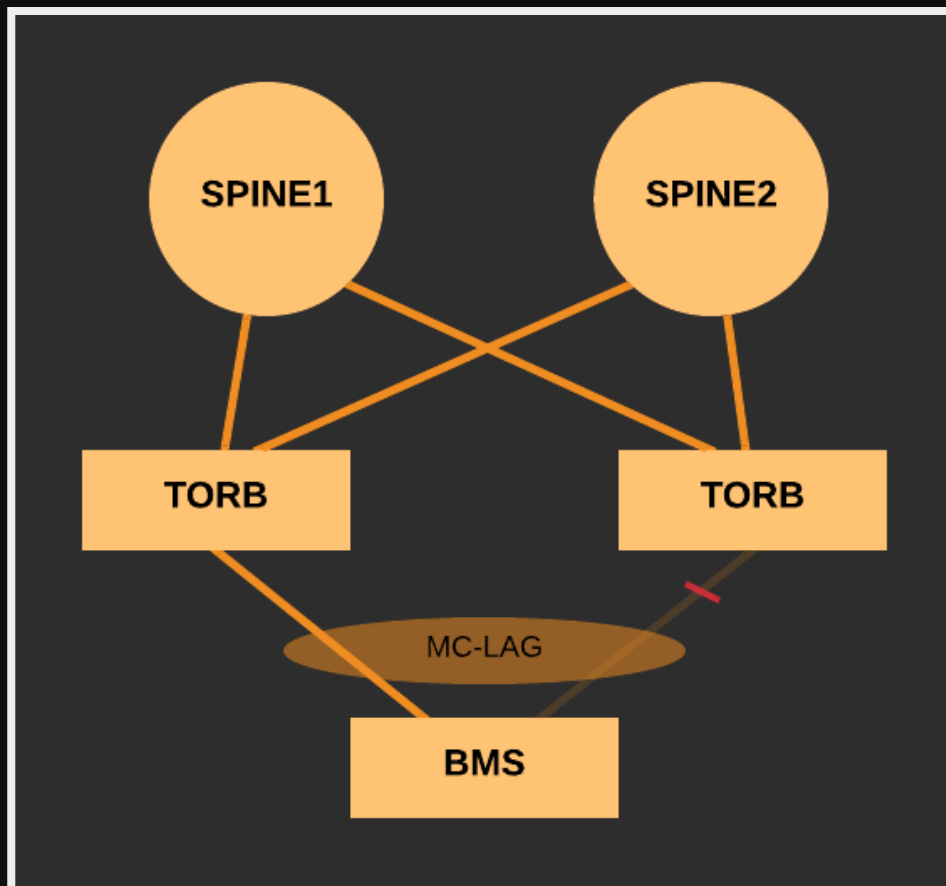
DC switches mass upgrade

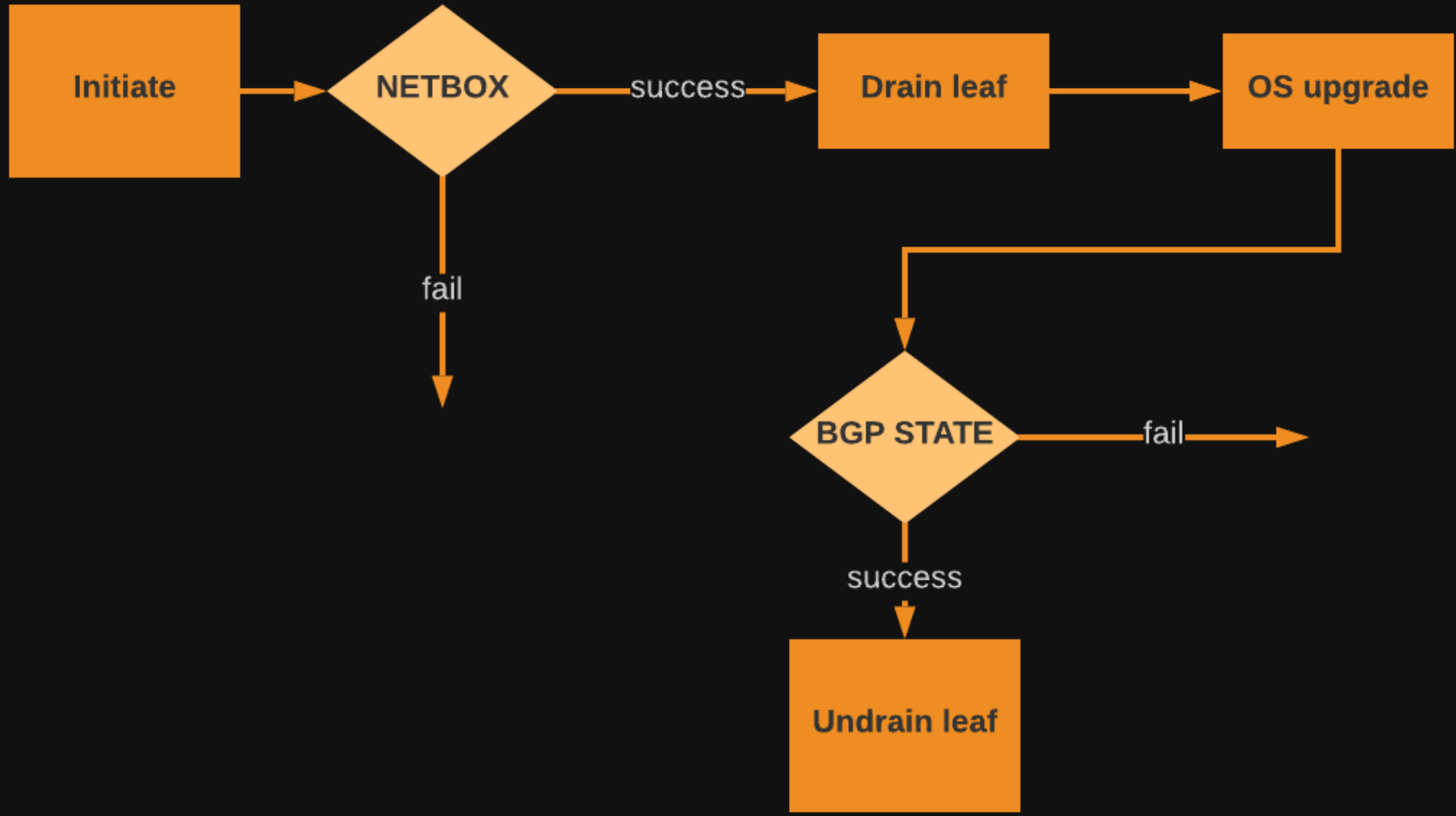
Our DCs architecture

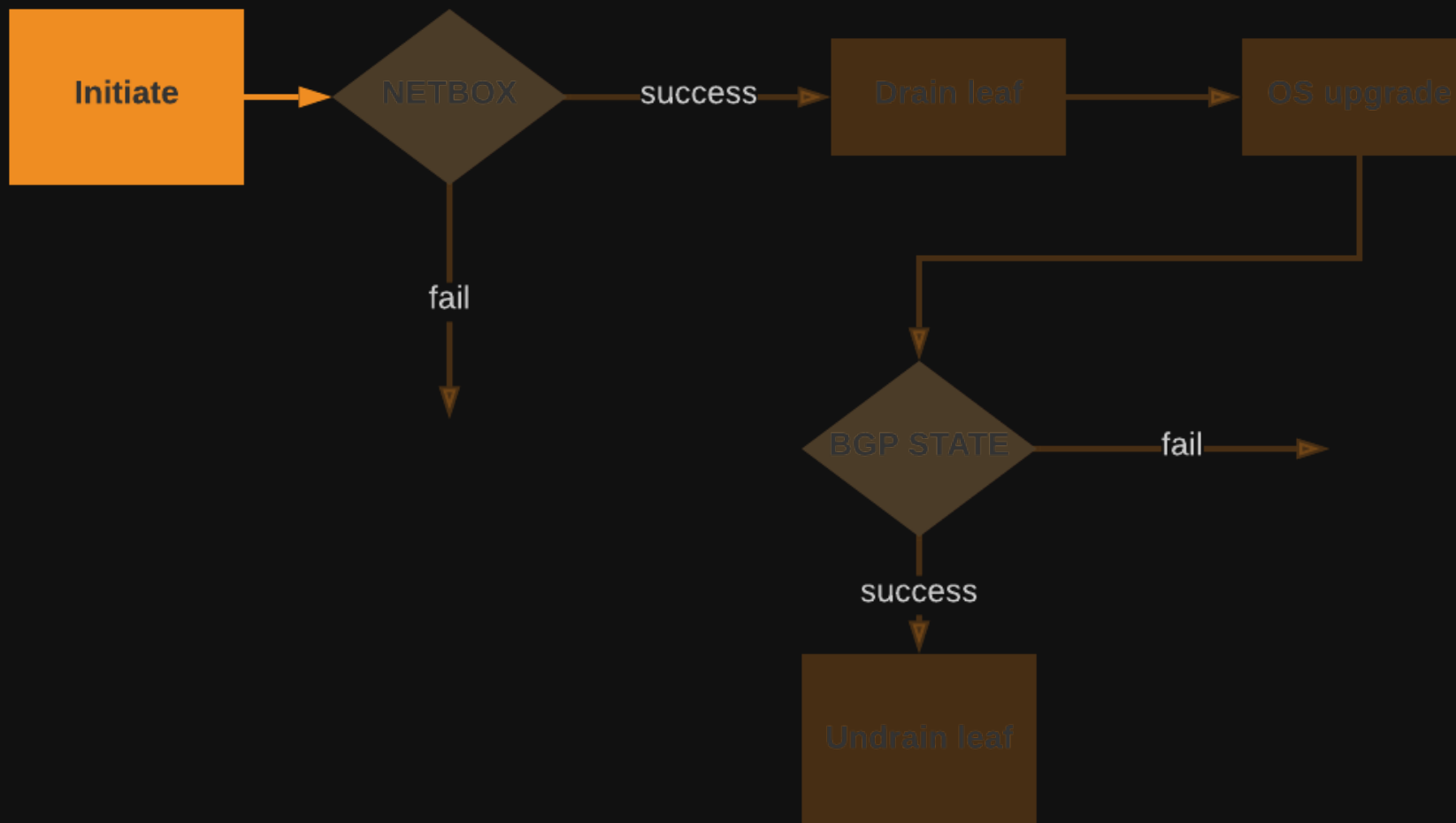


DC switches mass upgrade

Our DCs architecture



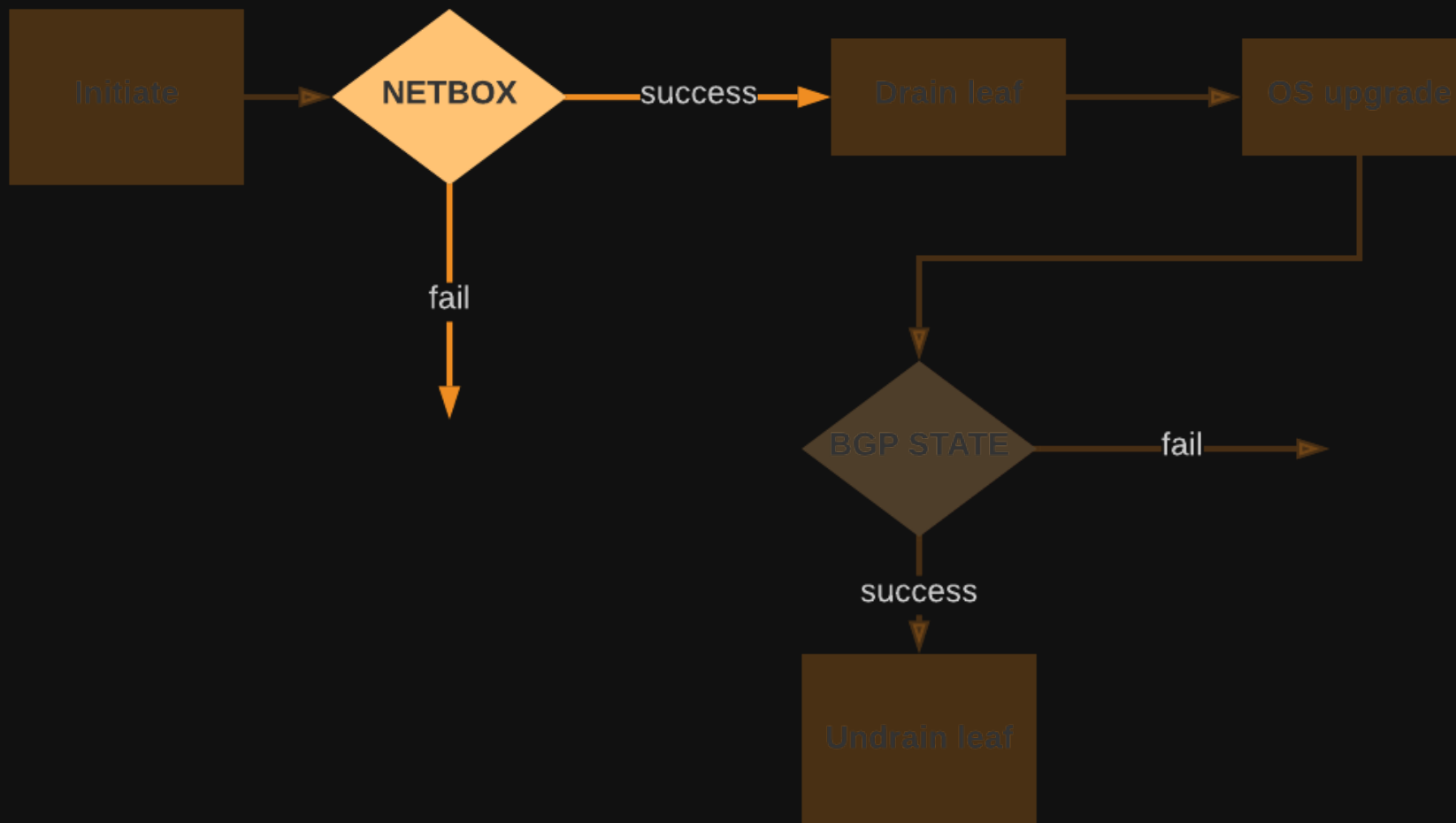




rules/upgrade-leaf.yaml



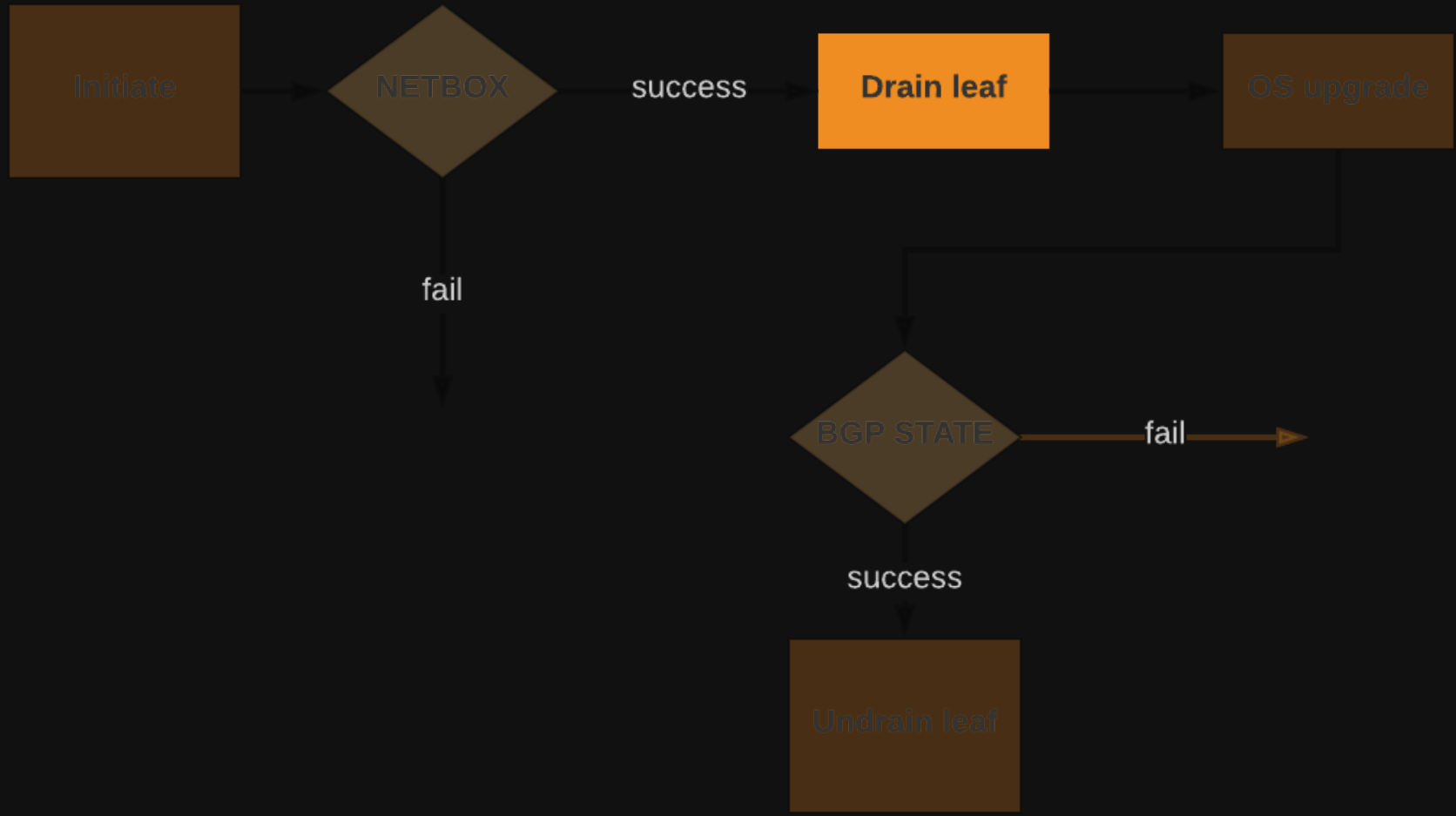
```
name: "upgrade_leaf"  
pack: "grnet"  
description: "Full workflow of the JunOS upgrade of a QFX5100"  
enabled: true  
trigger:  
  type: "core.st2.webhook"  
  parameters:  
    url: "upgrade_leaf"  
criteria: {}  
action:  
  ref: "grnet.upgrade-leaf"  
  parameters:  
    upgrade_data: "{{ trigger.body }}"
```



actions/workflows/upgrade-leaf.yaml



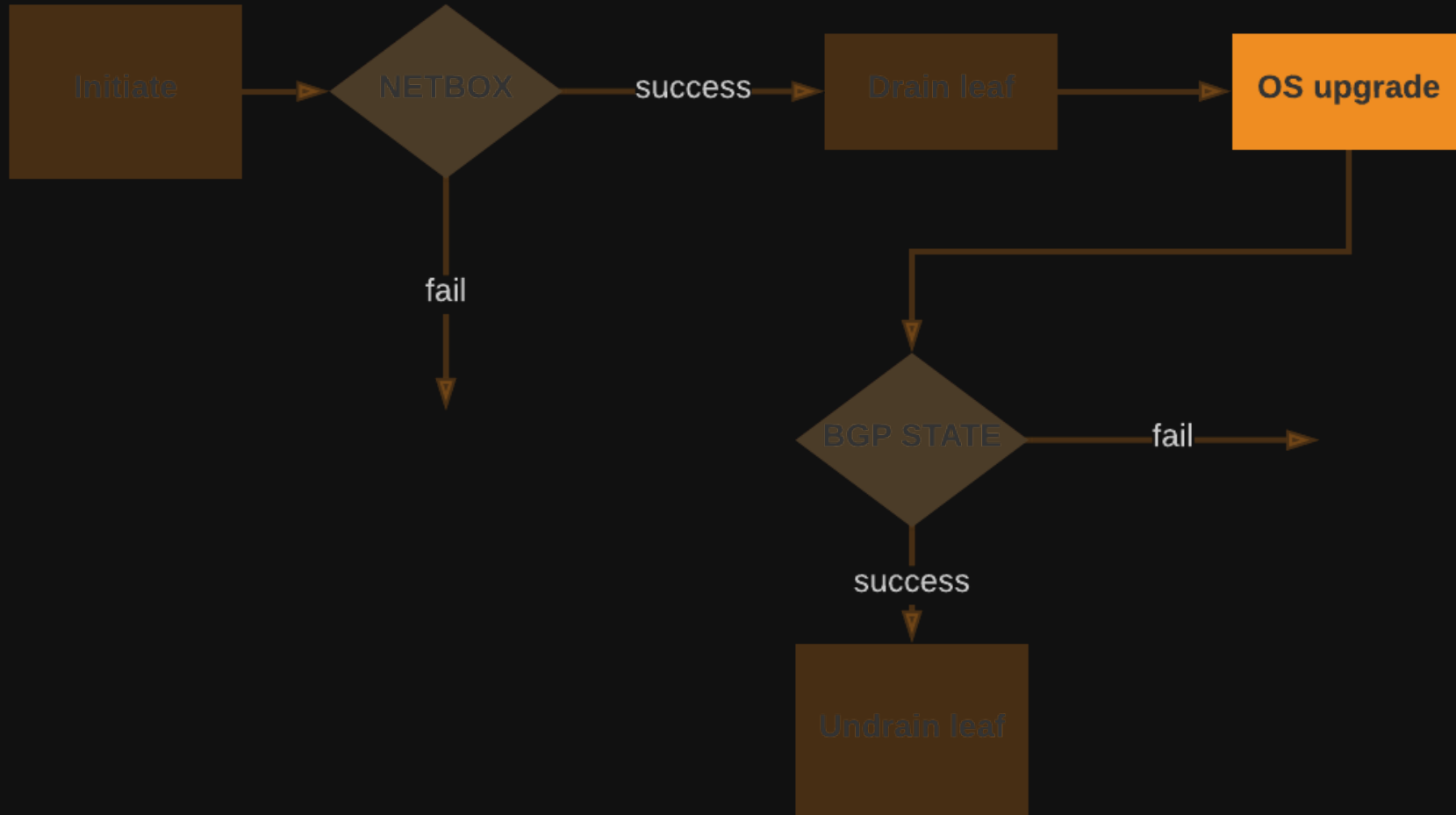
```
netbox_device:
  action: netbox.get.dcim.devices
  input:
    name: "{{ _dev_name }}"
  publish:
    dev_status: "{{ task('netbox_device')..status.label }}"
    dev_role: "{{ task('netbox_device')..device_role.slug }}"
  on-success:
    - fail: "{{ _dev_status != 'Active'
              or _dev_role != 'dc-fabric-leaf' }}"
    - bgp_status
    - admin_down_downlinks
```



actions/workflows/drain-leaf.yaml



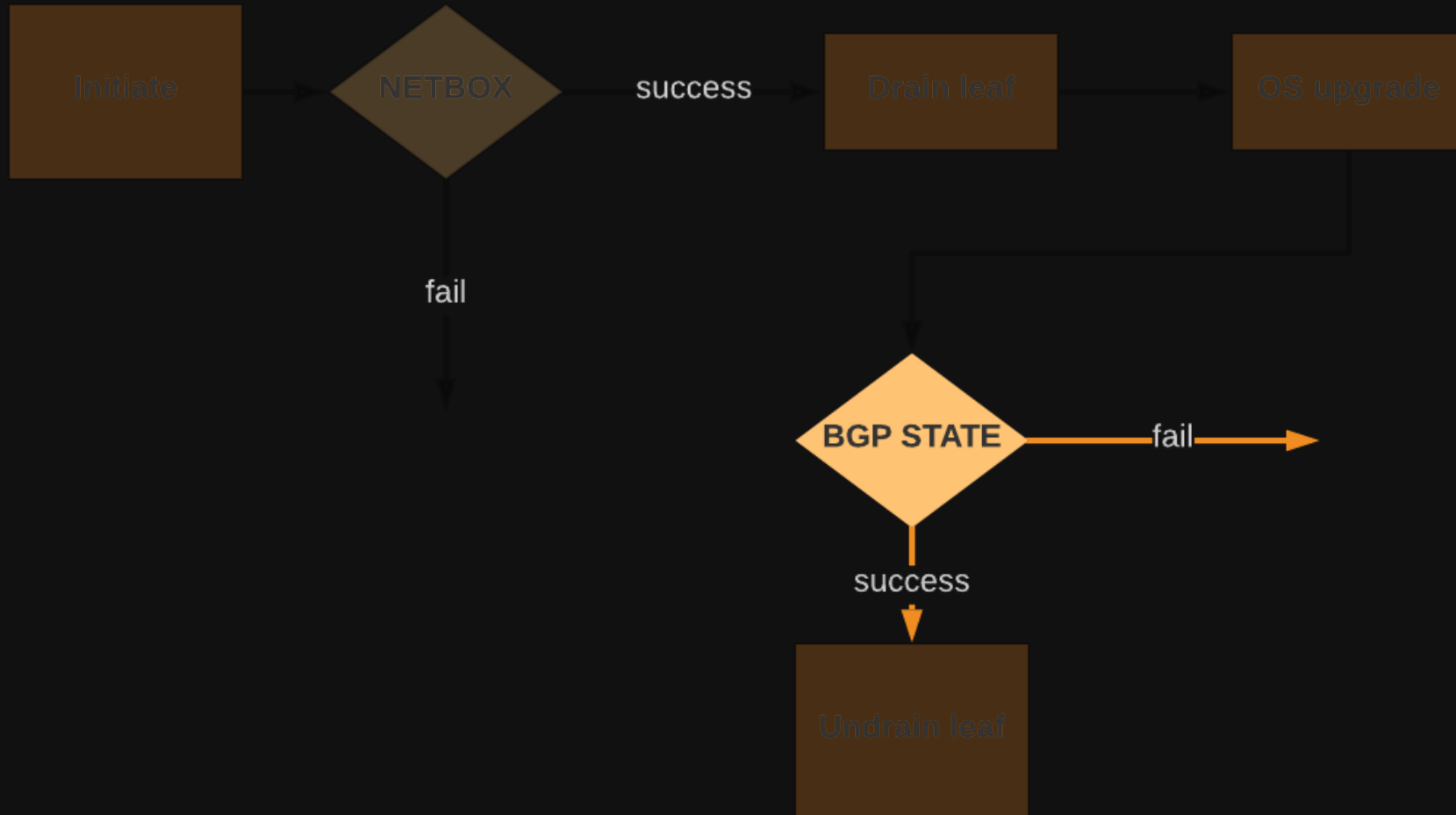
```
admin_down_downlinks:  
# Load the configuration that drains the switch  
action: napalm.loadconfig  
input:  
  config_file: "/srv/st2/static/drain_leaf_config.set"  
  hostname: "{{ _dev_name }}"  
  driver: "junos"
```



actions/workflows/junos-upgrade.yaml



```
qfx5100_upgrade:
  action: ansible.playbook
  input:
    playbook: "/srv/ansible/playbooks/junos-install.yaml"
    limit: "{{ _.dev_name }}"
    start_at_task: "Execute a basic Junos software upgrade"
    extra_vars:
      - user: "{{ }}"
      - password: "{{ st2kv.system.st2_devices_pass
                    | decrypt_kv }}"
      - force_host: true
      - remote_pkg: "{{ _.junos_url }}"
  on-success:
    - ping_host
```

actions/workflows/undrain-leaf.yaml



```
bgp_status:
  # Get the BGP status of the device leaf
  action: napalm.get_bgp_neighbors
  input:
    hostname: "{{ _ .dev_name }}"
    driver: "junos"
    credentials: "stackstorm"
  on-success:
    - evaluate_bgp_output
```

actions/workflows/undrain-leaf.yaml



```
evaluate_bgp_status:  
  action: grnet.evaluate_bgp_peers_status  
  input:  
    bgp_state: "{{ _ .bgp_after_status }}"  
  on-success:  
    - restore_port_state
```



actions/workflows/undrain-leaf.yaml



```
ansible_create_config:
  action: ansible.playbook
  input:
    playbook: "create-config.yml"
  on-success:
    - restore_port_state

restore_port_state:
  join: all
  action: ansible.playbook
  input:
    playbook: "junos-commit-and-confirm.yml"
```

some of our use cases

- Datacenter switches mass upgrade (done for leaf switches)
- Zero Touch Provisioning (done)
- Network Ops tasks part of BMS autoprovision (developing)
- Auto-deployment of our Ansible repo changes (brainstorming)

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- automate common tasks

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- trust automation for more critical tasks

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- runbooks all the way
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- can't automate the human

Questions?